

### 3 Stochastic Integrals

#### Exercise 3.1

(a) Since  $Z(t)$  is deterministic, we have

$$\begin{aligned}dZ(t) &= \alpha e^{\alpha t} dt \\ &= \alpha Z(t) dt.\end{aligned}$$

(b) By definition of a stochastic differential

$$dZ(t) = g(t) dW(t)$$

(c) Using Itô's formula

$$\begin{aligned}dZ(t) &= \frac{\alpha^2}{2} e^{\alpha W(t)} dt + \alpha e^{\alpha W(t)} dW(t) \\ &= \frac{\alpha^2}{2} Z(t) dt + \alpha Z(t) dW(t)\end{aligned}$$

(d) Using Itô's formula and considering the dynamics of  $X(t)$  we have

$$\begin{aligned}dZ(t) &= \alpha e^{\alpha X(t)} dX(t) + \frac{\alpha^2}{2} e^{\alpha X(t)} (dX(t))^2 \\ &= Z(t) \left[ \alpha \mu + \frac{1}{2} \alpha^2 \sigma^2 \right] dt + \alpha \sigma Z(t) dW(t).\end{aligned}$$

(e) Using Itô's formula and considering the dynamics of  $X(t)$  we have

$$\begin{aligned}dZ(t) &= 2X(t) dX(t) + (dX(t))^2 \\ &= Z(t) [2\alpha + \sigma^2] dt + 2Z\sigma dW(t).\end{aligned}$$

**Exercise 3.3** By definition we have that the dynamics of  $X(t)$  are given by  $dX(t) = \sigma(t) dW(t)$ .

Consider  $Z(t) = e^{iuX(t)}$ . Then using the Itô's formula we have that the dynamic of  $Z(t)$  can be described by

$$dZ(t) = \left[ -\frac{u^2}{2} \sigma^2(t) \right] Z(t) dt + [iu\sigma(t)] Z(t) dW(t)$$

From  $Z(0) = 1$  we get,

$$Z(t) = 1 - \frac{u^2}{2} \int_0^t \sigma^2(s) Z(s) ds + iu \int_0^t \sigma(s) Z(s) dW(s).$$

Taking expectations we have,

$$\begin{aligned} E[Z(t)] &= 1 - \frac{u^2}{2} E \left[ \int_0^t \sigma^2(s) Z(s) ds \right] + iu E \left[ \int_0^t \sigma(s) Z(s) dW(s) \right] \\ &= 1 - \frac{u^2}{2} \left[ \int_0^t \sigma^2(s) E[Z(s)] ds \right] + 0 \end{aligned}$$

By setting  $E[Z(t)] = m(t)$  and differentiating with respect to  $t$  we find an ordinary differential equation,

$$\frac{\partial m(t)}{\partial t} = -\frac{u^2}{2} m(t) \sigma^2(t)$$

with the initial condition  $m(0) = 1$  and whose solution is

$$\begin{aligned} m(t) &= \exp \left\{ -\frac{u^2}{2} \int_0^t \sigma^2(s) ds \right\} \\ &= E[Z(t)] \\ &= E \left[ e^{iuX(t)} \right] \end{aligned}$$

So,  $X(t)$  is normally distributed. By the properties of the normal distribution the following relation

$$E \left[ e^{iuX(t)} \right] = e^{iuE[X(t)] - \frac{u^2}{2} V[X(t)]}$$

where  $V[X(t)]$  is the variance of  $X(t)$ , so it must be that  $E[X(t)] = 0$  and  $V[X(t)] = \int_0^t \sigma^2(s) ds$ .

**Exercise 3.5** We have a sub martingale if  $E[X(t) | \mathcal{F}_s] \geq X(s) \forall, t \geq s$ . From the dynamics of  $X$  we can write

$$X(t) = X(s) + \int_s^t \mu(z) dz + \int_s^t \sigma(z) dW(z).$$

By taking expectation, conditioned at time  $s$ , from both sides we get

$$\begin{aligned} E[X(t) | \mathcal{F}_s] &= E[X(s) | \mathcal{F}_s] + E \left[ \int_s^t \mu(z) dz \middle| \mathcal{F}_s \right] \\ &= X(s) + E^s \left[ \underbrace{\int_s^t \mu(z) dz}_{\geq 0} \middle| \mathcal{F}_s \right] \\ &\geq X(s) \end{aligned}$$

so  $X$  is a sub martingale.

**Exercise 3.6** Set  $X(t) = h(W_1(t), \dots, W_n(t))$ .

We have by Itô that

$$dX(t) = \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(t) + \frac{1}{2} \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} dW_i(t) dW_j(t)$$

where  $\frac{\partial h}{\partial x_i}$  denotes the first derivative with respect to the  $i$ -th variable,  $\frac{\partial^2 h}{\partial x_i \partial x_j}$  denotes the second order cross-derivative between the  $i$ -th and  $j$ -th variable and all derivatives should be evaluated at  $(W_1(s), \dots, W_n(s))$ .

Since we are dealing with independent Wiener processes we know

$$\forall u: \quad dW_i(u) dW_j(u) = 0 \text{ for } i \neq j \quad \text{and} \quad dW_i(u) dW_j(u) = du \text{ for } i = j,$$

so, integrating we get

$$\begin{aligned} X(t) &= \int_0^t \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) + \frac{1}{2} \int_0^t \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} dW_i(u) dW_j(u) \\ &= \int_0^t \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) + \frac{1}{2} \int_0^t \sum_{i=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} [dW_i(u)]^2 \\ &= \int_0^t \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) + \frac{1}{2} \int_0^t \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} du. \end{aligned}$$

Taking expectations

$$\begin{aligned} E[X(t) | \mathcal{F}_s] &= E \left[ \int_0^t \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) \middle| \mathcal{F}_s \right] + E \left[ \frac{1}{2} \int_0^t \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} du \middle| \mathcal{F}_s \right] \\ &= \underbrace{\int_0^s \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) + \frac{1}{2} \int_0^s \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} du}_{X(s)} \\ &\quad + E \left[ \underbrace{\int_0^t \sum_{i=1}^n \frac{\partial h}{\partial x_i} dW_i(u) \middle| \mathcal{F}_s}_0 \right] + E \left[ \frac{1}{2} \int_s^t \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} du \middle| \mathcal{F}_s \right] \\ &= X(s) + E \left[ \frac{1}{2} \int_s^t \sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} du \middle| \mathcal{F}_s \right]. \end{aligned}$$

- If  $h$  is *harmonic* the last term is zero, since  $\sum_{i,j=1}^n \frac{\partial^2 h}{\partial x_i \partial x_j} = 0$ , we have

$$E[X(t) | \mathcal{F}_s] = X(s) \quad \text{so } X \text{ is a martingale.}$$